

# PART 12

## KNAPSACK

SOURCE: *Approximation Algorithms* (Vazirani, Springer Press)

# Knapsack

## Problem: KNAPSACK

- ▶ Given:  $n$  objects with weight  $w_i \in \mathbb{Q}_+$  and profit  $p_i \in \mathbb{Q}_+$ , size  $G \in \mathbb{Q}_+$
- ▶ Find: Subset of objects, maximizing the profit and not exceeding the weight bound:

$$OPT = \max_{I \subseteq \{1, \dots, n\}} \left\{ \sum_{i \in I} p_i \mid \sum_{i \in I} w_i \leq G \right\}$$

# A dynamic program for KNAPSACK

## Dynamic program:

- (1) Assume restricted profits  $p_i \in \{0, \dots, B\}$
- (2) Compute table entries

$$\begin{aligned} T(i, b) &= \min_{I \subseteq \{1, \dots, i\}} \left\{ \sum_{j \in I} w_j \mid \sum_{j \in I} p_j \geq b \right\} \\ &= \text{minimum weight needed for a subset of the first } i \\ &\quad \text{objects to obtain a profit of at least } b \end{aligned}$$

using dynamic programming

$$T(i, b) = \min \left\{ \underbrace{T(i-1, b)}_{\text{don't take } i}, \underbrace{T(i-1, b - p_i) + w_i}_{\text{take } i} \right\} \quad \forall i \quad \forall p = 0, \dots, B$$

- (3) Reconstruct  $I$  leading to  $\max\{b \in \mathbb{N}_0 \mid T(n, b) \leq G\}$

## Observation

The algorithm finds optimum solutions in time  $O(n \cdot B)$ .

# The FPTAS

## Algorithm:

- (1) Scale profits s.t.  $p_{\max} = n/\varepsilon$
- (2) Round  $p'_i := \lfloor p_i \rfloor$
- (3) Compute and return optimum solution  $I$  for weights  $p'_i$

# Analysis of FPTAS

## Theorem

Let  $0 < \varepsilon \leq \frac{1}{2}$ . The algo gives a  $(1 + 2\varepsilon)$ -apx in time  $O(n^2/\varepsilon)$ .

- ▶ W.l.o.g.  $OPT \geq p_{\max} = n/\varepsilon$  (we can delete objects that even alone do not fit into the knapsack)
- ▶ Let  $I^*$  be optimum solution for original profits. Let  $OPT'$  be optimum value for profits  $p'$ . Then

$$\begin{aligned} OPT' &\geq \sum_{i \in I^*} p'_i = \sum_{i \in I^*} \lfloor p_i \rfloor \geq \sum_{i \in I^*} p_i - |I^*| \geq OPT - n \\ &\geq (1 - \varepsilon)OPT \geq \frac{OPT}{1 + 2\varepsilon} \end{aligned}$$

- ▶ Let  $I$  be solution found by dynamic program:

$$\sum_{i \in I} p_i \geq \sum_{i \in I} p'_i = OPT' \geq \frac{OPT}{1 + 2\varepsilon}$$

- ▶  $B = \max\{p'_i\} \leq n/\varepsilon$  hence the running time is  $O(n^2/\varepsilon)$

PART 13  
MULTI CONSTRAINT KNAPSACK

SOURCE: Folklore

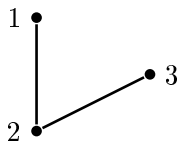
# Multi Constraint Knapsack

## Problem: MULTI CONSTRAINT KNAPSACK (MCK)

- ▶ Given:  $n$  objects with profits  $p_i \in \mathbb{Q}_+$  and  $k$  many budgets  $B_j$ . Object  $i$  has requirement  $a_i^j \in \mathbb{Q}_+$  w.r.t. budget  $j$ .
- ▶ Find: Subset of objects, maximizing the profit and not exceeding any budget:

$$OPT = \max_{I \subseteq \{1, \dots, n\}} \left\{ \sum_{i \in I} p_i \mid \sum_{i \in I} a_i^j \leq B_j \quad \forall j = 1, \dots, k \right\}$$

- ▶ For arbitrary  $k$  there is no  $n^{1-\epsilon}$ -apx: Take an INDEPENDENT SET instance  $G = (V, E)$ . For each edge  $e = (u, v)$  add an “edge budget constraint”  $a_u^e = a_v^e = 1, B_e = 1$ . Then  $OPT = OPT_{IS}$ .



$$\Rightarrow \begin{array}{rcll} \max & x_1 & +x_2 & +x_3 \\ & 1x_1 & +1x_2 & +0x_3 \leq 1 \\ & 0x_1 & +1x_2 & +1x_3 \leq 1 \\ & & & x_i \in \{0, 1\} \end{array}$$

# A PTAS for $k = O(1)$

## Algorithm:

- (1) Guess the  $\lceil \frac{k}{\varepsilon} \rceil$  items  $I_{\text{large}}$  in the optimum solution with maximum profit
- (2) Let  $x^*$  be optimum basic solution to the following LP

$$\begin{aligned} \max \quad & \sum_{i=1}^n x_i p_i \\ \text{s.t.} \quad & \sum_{i=1}^n a_i^j x_i \leq B_j \quad \forall j = 1, \dots, k \\ & x_i = 1 \quad \forall i \in I_{\text{large}} \\ & x_i = 0 \quad \forall i \notin I_{\text{large}} : p_i > \min\{p_j \mid j \in I_{\text{large}}\} \\ & 0 \leq x_i \leq 1 \quad \forall i = 1, \dots, n \end{aligned}$$

- (3) Output  $I := \{i \mid x_i^* = 1\}$ .



# The Analysis

## Theorem

For constant  $k$  the algorithm has polynomial running time.  
Furthermore  $APX \geq (1 - \varepsilon)OPT$ .

- ▶ The produced solution is clearly feasible
- ▶  $LP \geq OPT$  (since we guess elements from  $OPT$ )
- ▶ Observation:  $|\{i \mid 0 < x_i^* < 1\}| \leq k$  since  $x^*$  is a basic solution and apart from  $0 \leq \dots \leq 1$  there are only  $k$  constraints.
- ▶ For  $i$  with  $0 < x_i^* < 1$  one has  $p_i \leq \frac{\varepsilon}{k}OPT$

$$\begin{aligned} APX &\geq \sum_{i=1}^n \lfloor x_i^* \rfloor p_i \geq LP - \underbrace{\sum_{i: 0 < x_i^* < 1} p_i}_{\leq k \cdot \frac{\varepsilon}{k} OPT} \\ &\geq OPT - k \cdot \frac{\varepsilon}{k} OPT = (1 - \varepsilon)OPT \end{aligned}$$



# Hardness of MULTICONSTRAINTKNAPSACK

## Theorem

There is no FPTAS for MULTICONSTRAINTKNAPSACK even for 2 budgets, unless  $\mathbf{NP} = \mathbf{P}$ .

## Problem: PARTITION

- ▶ Given: Numbers  $a_1, \dots, a_n \in \mathbb{N}$ ,  $S := \sum_{i=1}^n a_i$ ,  
 $m \in \{1, \dots, n\}$
- ▶ Find:  $I \subseteq \{1, \dots, n\} : |I| = m, \sum_{i \in I} a_i = S/2$

- ▶ Recall: PARTITION is  $\mathbf{NP}$ -hard.
- ▶ Define MCK instance with 2 constraints:

$$\begin{aligned} \max \quad & \sum_{i=1}^n x_i \\ & \sum_{i=1}^n x_i a_i \leq S/2 \\ & \sum_{i=1}^n x_i (S - a_i) \leq S(m - \frac{1}{2}) \\ & x_i \in \{0, 1\} \quad \forall i = 1, \dots, n \end{aligned}$$

# Proof

- ▶ Claim:  $\exists$  PARTITION solution  $\Leftrightarrow OPT_{\text{MCK}} \geq m$
- ▶  $\Rightarrow$  Suppose  $\exists I : |I| = m, \sum_{i \in I} a_i = S/2$ . Then this is a MCK solution of value  $m$  since

$$\sum_{i \in I} (S - a_i) = mS - \sum_{i \in I} a_i = S(m - \frac{1}{2})$$

- ▶  $\Leftarrow$  Let  $I$  be MCK solution of value  $\geq m$ .

$$|I| \cdot S - \frac{S}{2} \stackrel{1. \text{ constr.}}{\leq} |I| \cdot S - \underbrace{\sum_{i \in I} a_i}_{\leq S/2} = \sum_{i \in I} (S - a_i) \stackrel{2. \text{ const.}}{\leq} m \cdot S - \frac{S}{2}$$

- ▶ Hence  $|I| = m$ . Then ineq. holds with "="
- ▶ Thus  $\sum_{i \in I} a_i = S/2$ . □
- ▶ Now suppose for contradiction we would have an FPTAS for MCK: Then choose  $\varepsilon := \frac{1}{n+1}$ . Then the FPTAS would give an optimum solution for the instance resulting from the PARTITION reduction.

# PART 14

## BIN PACKING

SOURCE: *Combinatorial Optimization: Theory and Algorithms*  
(Korte, Vygen)

# Bin Packing

## Problem: BINPACKING

- ▶ Given: Items with sizes  $a_1, \dots, a_n \in [0, 1]$
- ▶ Find: Assign items to minimum number of bins of size 1.

$$OPT = \min \left\{ k \mid \exists I_1 \dot{\cup} \dots \dot{\cup} I_k = \{1, \dots, n\} : \forall j : \sum_{i \in I_j} a_i \leq 1 \right\}$$

- ▶ Define  $\text{size}(I) = \sum_{i \in I} a_i$

# First Fit

## First Fit algorithm:

- (1) Start with empty bins
- (2) FOR  $i = 1, \dots, n$  DO
  - (3) Assign item  $i$  to the bin  $B$  with least index such that
$$a_i + \sum_{j \in B} a_j \leq 1$$

## Lemma

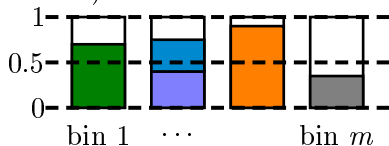
Let  $m$  be the number of used bins. Then

$$m \leq 2 \sum_{i=1}^n a_i + 1 \leq 2 \cdot OPT + 1.$$

- ▶ All but  $m - 1$  bins must be filled with  $\geq \frac{1}{2}$  (otherwise we would not have opened a new bin):

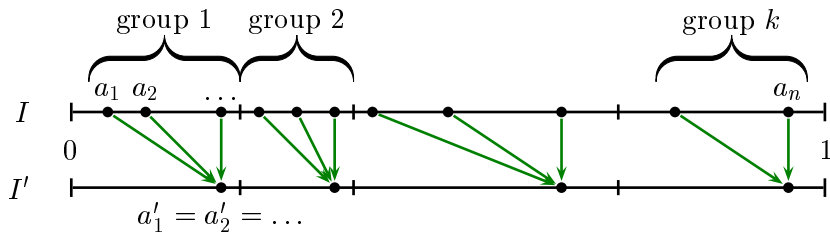
$$\sum_{i=1}^n a_i \geq \frac{1}{2}(m - 1)$$

- ▶ Hence  $m \leq 2 \sum_{i=1}^n a_i + 1$ .



# Linear Grouping

- ▶ INPUT: Instance  $I = (a_1, \dots, a_n)$ ,  $k \in \mathbb{N}$
  - ▶ OUTPUT: Instance  $I' = (a'_1, \dots, a'_n)$  with  $a'_i \geq a_i$  and  $\leq k$  different item sizes
- (1) Sort  $a_1 \leq a_2 \leq \dots \leq a_n$
  - (2) Partition items into  $k$  consecutive groups of  $\lceil n/k \rceil$  items (the last group might have less items)
  - (3) Let  $a'_i$  be the size of the largest item in  $i$ 's group

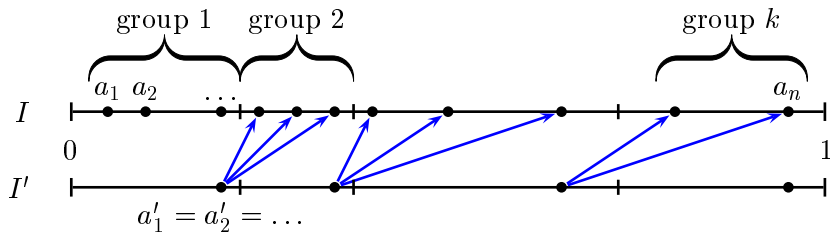


## Linear Grouping (2)

### Lemma

$$OPT(I') \leq OPT(I) + \lceil n/k \rceil.$$

- ▶ Consider solution  $OPT(I)$ . Assign item  $a'_i$  of group  $j$  to a space for item in group  $j + 1$
- ▶ Assign largest  $\lceil n/k \rceil$  items to their own bin





# An asymptotic PTAS

## Algorithm of Fernandez de la Vega & Lueker:

- (1) Let  $I = \{i \mid a_i > \varepsilon\}$  be set of large items (other items are small)
- (2) Apply linear grouping with  $k = 1/\varepsilon^2$  groups to  $I \rightarrow I'$
- (3) Compute an optimum distribution of  $I'$
- (4) Distribute the small items over the used bins using First Fit

## Lemma

*The algorithm runs in polynomial time and uses at most  $(1 + 2\varepsilon)OPT + 1$  bins.*

- ▶ Let  $b_1, \dots, b_{1/\varepsilon^2}$  different item sizes in  $I'$ .
- ▶ Possible bin configurations  
 $\mathcal{P} = \{p \in \{0, \dots, 1/\varepsilon\}^{1/\varepsilon^2} \mid b^T p \leq 1\}$ .  $|\mathcal{P}| \leq (1/\varepsilon^2)^{1/\varepsilon}$ .
- ▶ Solution is described by  $(n_p)_{p \in \mathcal{P}}$  ( $n_p =$  how many times shall I pack a bin with configuration  $p?$ ),  $n_p \in \{0, \dots, n\}$
- ▶  $\leq n^{(1/\varepsilon^2)^{1/\varepsilon}}$  possibilities for  $(n_p)_{p \in \mathcal{P}}$ .

## An asymptotic PTAS (2)

- ▶ We need  $OPT(I') + \#$  of bins additionally opened for the small items
- ▶ Note that

$$OPT(I') \leq OPT(I) + \lceil |I| \cdot \varepsilon^2 \rceil \leq OPT(I) + \lceil \varepsilon \cdot OPT(I) \rceil = (1 + 2\varepsilon) \cdot OPT$$

using  $OPT(I) \geq \sum_{i \in I} a_i \geq \varepsilon \cdot |I|$  and  $OPT \geq OPT(I)$ .

- ▶ Suppose we need to open an additional bin for small items. Let  $m$  be total number of used bins. Then all but one bin are filled to  $\geq 1 - \varepsilon$ . Hence

$$OPT \geq \sum_{i=1}^m a_i \geq (1 - \varepsilon) \cdot (m - 1)$$

and

$$m \leq \frac{OPT}{1 - \varepsilon} + 1 \leq (1 + 2\varepsilon)OPT + 1$$

SECTION 14.1  
THE ALGORITHM OF KARMARKAR & KARP

# The Algorithm of Karmarkar & Karp

Theorem (Karmarkar, Karp '82)

*One can compute a BINPACKING solution with  $OPT + O(\log^2 n)$  many bins in polynomial time.*

- ▶ Assume  $a_i \geq \delta := \frac{1}{n}$  (again one can distribute items that are smaller than  $\frac{1}{n}$  after distributing the large items).

# The Gilmore-Gomory LP-relaxation

- ▶ Let  $b_i \in \mathbb{N}$  now the number of items of size  $a_i$
- ▶  $n$  = number of different item sizes
- ▶  $m := \sum_{i=1}^n b_i$  = total number of items
- ▶  $\mathcal{P} = \{p \in \mathbb{Z}_+^n \mid a^T p \leq 1\}$  set of feasible patterns
- ▶ Variable  $x_p = \#$  of bins packed with pattern  $p$

## Primal

$$\begin{aligned} \min \mathbf{1}^T x & \quad (P(\mathcal{P})) \\ \sum_{p \in \mathcal{P}} x_p p & \geq b \\ x & \geq \mathbf{0} \end{aligned}$$

- ▶ # var. **exponential**
- ▶ # constr. **polynomial**

## Dual

$$\begin{aligned} \max y^T b & \quad (D(\mathcal{P})) \\ p^T y & \leq 1 \quad \forall p \in \mathcal{P} \\ y & \geq \mathbf{0} \end{aligned}$$

- ▶ # var. **polynomial**
- ▶ # constr. **exponential**

**Idea:** Solve the dual with Ellipsoid!

# Example

- ▶ Item sizes  $a_1 = 0.3, a_2 = 0.4$
- ▶ # of items  $b_1 = 31, b_2 = 7$
- ▶ Set of patterns  $\mathcal{P} = \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \end{pmatrix} \right\}$

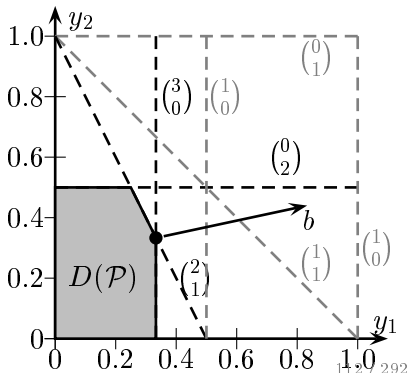
## Primal

$$\begin{aligned} \min \mathbf{1}^T x \\ \begin{pmatrix} 0 & 0 & 1 & 2 & 1 & 2 & 3 \\ 1 & 2 & 1 & 1 & 0 & 0 & 0 \end{pmatrix} x &\geq \begin{pmatrix} 31 \\ 7 \end{pmatrix} \\ x &\geq \mathbf{0} \end{aligned}$$

- ▶ Opt basic solution is  $x = (0, 0, 0, 7, 0, 0, \frac{17}{3})$

## Dual

$$\begin{aligned} \max 31y_1 + 7y_2 \\ \begin{pmatrix} 0 & 1 \\ 0 & 2 \\ 1 & 1 \\ 2 & 1 \\ 1 & 0 \\ 2 & 0 \\ 3 & 0 \end{pmatrix} y &\leq \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \\ y &\geq \mathbf{0} \end{aligned}$$



# Weak Separation Problem

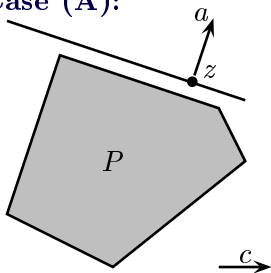
$\varepsilon$ -Weak Separation Oracle for  $P \subseteq \mathbb{R}^n$ , obj.fct.  $c \in \mathbb{Q}^n$

INPUT: Vector  $z \in \mathbb{Q}^n$

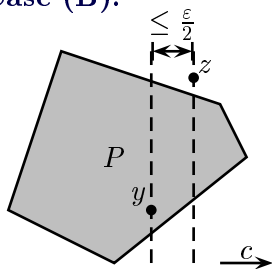
OUTPUT: One of the following

- ▶ *Case (A)*: Vector  $a$  with  $a^T x \leq a^T z \forall x \in P$
- ▶ *Case (B)*: Point  $y \in P$  with  $c^T y \geq c^T z - \frac{\varepsilon}{2}$

**Case (A):**



**Case (B):**

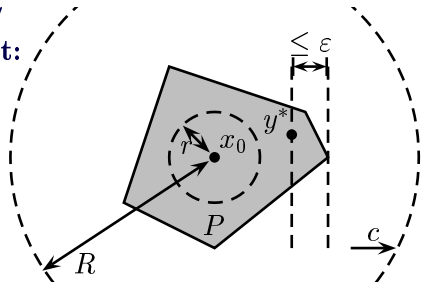


- ▶ If  $z \in P$ , just return  $z$  ( $\rightarrow$  case (B)).

# Grötschel-Lovász-Schrijver Algorithm

- ▶ INPUT:  $c \in \mathbb{Q}^n, x_0 \in \mathbb{Q}^n, \varepsilon, r, R \in \mathbb{Q}_+$  :  
 $B(x_0, r) \subseteq P \subseteq B(x_0, R)$
- ▶ OUTPUT:  $y^* \in P$  with  $c^T y^* \geq OPT_f - \varepsilon$
- (1) Ellipsoid  $E_0 := B(x_0, R)$  with center  $z_0 := x_0, y^* := x_0$
- (2) FOR  $t = 0, \dots, poly$  DO
  - (4) Submit  $z_t$  to  $\varepsilon$ -weak separation oracle
  - (5) Case (A)  $\rightarrow a$ : Compute  $E_{t+1} \supseteq E_t \cap \{x \mid a^T x \leq a^T z_t\}$
  - (6) Case (B)  $\rightarrow y \in P$ :
    - (7) IF  $c^T y > c^T y^*$  THEN  $y^* := y$
    - (8) Compute  $E_{t+1} \supseteq E_t \cap \{x \mid c^T x \geq c^T z_t\}$

**Input/  
Output:**

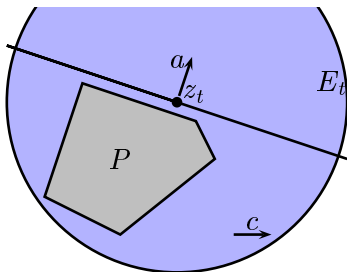




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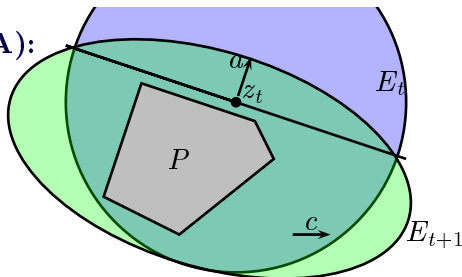
Case (A):



# Grötschel-Lovász-Schrijver Algorithm

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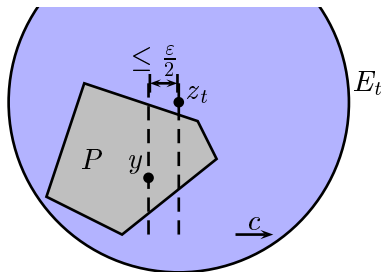
Case (A):



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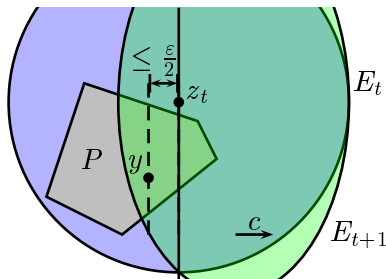
**Case (B):**



# Grötschel-Lovász-Schrijver Algorithm

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**Case (B):**



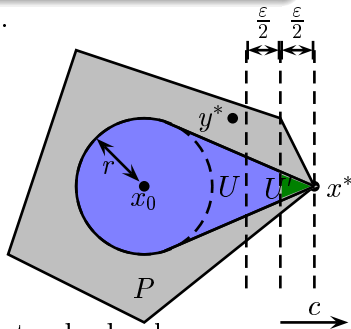
# Analysis

## Theorem

Let  $OPT_f = \max\{c^T x \mid x \in P\}$ . The GLS algorithm finds a  $y^* \in P$  with  $c^T y^* \geq OPT_f - \varepsilon$ .

- ▶ Suppose for contradiction this is false.
- ▶ Let  $x^* \in P$  be opt. sol.;  $\varphi$  input size.
- ▶ Inequalities from case (A) never cut points from  $P$
- ▶ Ineq. from case (B) never cut points better than  $OPT_f - \frac{\varepsilon}{2}$  (otherwise we would have found a suitable  $y^*$ )
- ▶ Let  $U := \text{conv}\{B(x_0, r), x^*\}$  and  $U' = \{x \in U \mid c^T x \geq OPT_f - \frac{\varepsilon}{2}\}$ . By standard volume bounds:  $\text{vol}(U') \geq (\frac{1}{2})^{\text{poly}(\varphi)}$ . But  $U' \subseteq E_t \forall t$ . After  $\text{poly}(\varphi)$  many it.  $\text{vol}(E_t) = (1 - \frac{\Theta(1)}{n})^t \cdot \text{vol}(E_0) < \text{vol}(U')$ .

**Contradiction!**

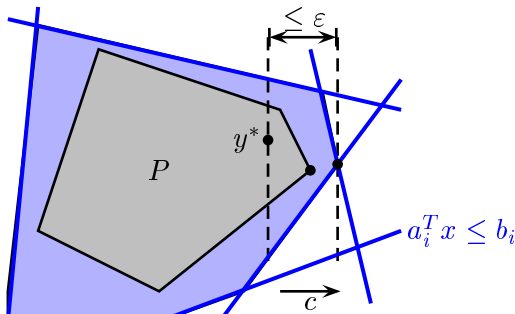


# A useful observation

## Observation

Consider a run of the GLS algorithm for  $P \subseteq \mathbb{R}^n$  which yields  $y^* \in P$ . Let  $a_1^T x \leq b_1, \dots, a_N^T x \leq b_N$  be the inequalities which the oracle are returned for Case (A).

- ▶ Each  $a_i^T x \leq b_i$  is feasible for  $P$
- ▶  $c^T y^* \geq \max\{c^T x \mid a_i^T x \leq b_i \forall i = 1, \dots, N\} - \varepsilon$



# Solving $D(\mathcal{P})$

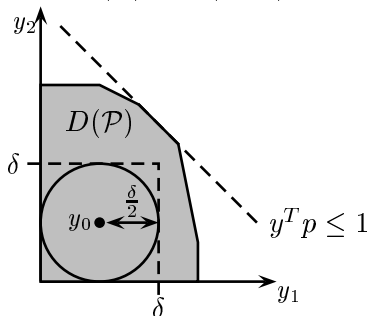
## Lemma

Suppose  $a_i \geq \delta$ . Then we can find a feasible solution  $y^*$  to  $D(\mathcal{P})$  of value  $\geq OPT_f - 1$  in time polynomial in  $n, m, \frac{1}{\delta}$ .

- ▶ Apply GLS algo for  $\varepsilon := 1$ . Choose  $y_0 = (\frac{\delta}{2}, \dots, \frac{\delta}{2})$ .

$$B\left(y_0, \frac{\delta}{2}\right) \stackrel{(\delta, \dots, \delta)^T p \leq 1}{\subseteq} D(\mathcal{P}) \subseteq B(y_0, n)$$

- ▶ We use  $\sum_{i=1}^n p_i \leq \frac{1}{\delta}$  for any feasible pattern  $p \in \mathcal{P}$  since  $a_i \geq \delta$

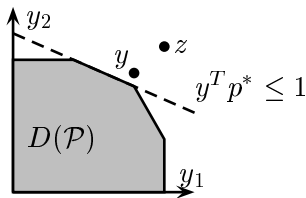


## Solving $D(\mathcal{P})$ (2)

- ▶ We solve  $\varepsilon$ -weak separation problem for  $z \in \mathbb{Q}^n$ .
- ▶ If  $z_i < 0 \rightarrow$  Case (A) (inequality  $z_i \geq 0$  violated)
- ▶ If  $z_i > 1 \rightarrow$  Case (A) (inequality  $z^T e_i \leq 1$  violated)
- ▶ Round  $z$  down to nearest multiple of  $\frac{1}{2m}$  and term this vector  $y$ . Solve  $p^* = \operatorname{argmax}\{y^T p \mid p \in \mathcal{P}\}$   
(KNAPSACK with profits from  $0, 1 \cdot \frac{1}{2m}, 2 \cdot \frac{1}{2m}, \dots, 1$ )

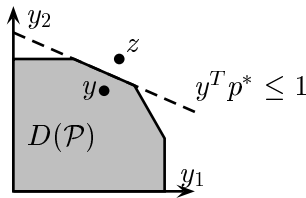
### Case $y^T p^* > 1$ :

- ▶ Then  $z^T p^* \geq y^T p^* > 1$   
 $\rightarrow$  Case (A).



### Case $y^T p^* \leq 1$ :

- ▶ Then  $y \in D(\mathcal{P})$ . And  
 $z^T b - y^T b \leq m \cdot \frac{1}{2m} = \frac{1}{2} = \frac{\varepsilon}{2}$   
 $\rightarrow$  Case (B)



- ▶ GLS yields a solution  $y^*$  mit  $b^T y^* \geq OPT_f - 1$ .





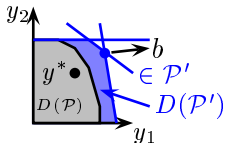
# Finding a near optimal basic solution for $P(\mathcal{P})$

## Theorem

Suppose  $a_i \geq \delta$ . Then we can find a basic solution  $x^*$  for  $P(\mathcal{P})$  of value  $\leq OPT_f + 1$  in time polynomial in  $n, m, \frac{1}{\delta}$ .

- ▶ Run GLS to obtain sol.  $y^*$  to  $D(\mathcal{P})$  with  $b^T y^* \geq OPT_f - 1$
- ▶ Let  $y^T p \leq 1, p \in \mathcal{P}'$  be inequalities returned by oracle for case (A).  $\mathcal{P}' \subseteq \mathcal{P}$  has polynomial size and

$$D(\mathcal{P}) \stackrel{y^* \text{ valid for } D(\mathcal{P})}{\geq} b^T y^* \geq D(\mathcal{P}') - 1 \quad (1)$$



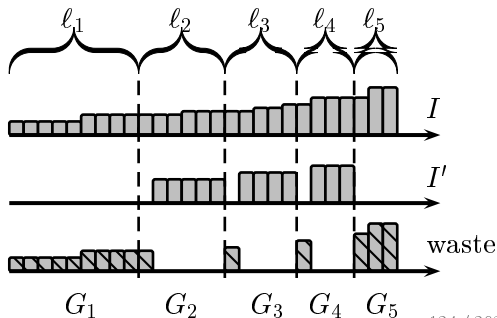
- ▶ Compute optimum basic solution  $x^*$  for  $P(\mathcal{P}')$  in poly-time.

$$\mathbf{1}^T x^* = P(\mathcal{P}') \stackrel{\text{duality}}{=} D(\mathcal{P}') \stackrel{(1)}{\leq} D(\mathcal{P}) + 1 \stackrel{\text{duality}}{=} P(\mathcal{P}) + 1$$

- ▶  $x^*$  is also a (non-optimal) basic solution for  $P(\mathcal{P})$

# Geometric Grouping

- ▶ INPUT: Instance  $I = (a_1, \dots, a_n)$ ,  $size(I) = \sum_{i=1}^n a_i b_i \leq n$ ,  $a_i \geq \delta$
  - ▶ OUTPUT: Rounded up instance  $I'$  with  $n/2$  diff. item sizes  $OPT_f(I') \leq OPT_f(I)$  plus waste of  $O(\log \frac{1}{\delta})$
- (1) Sort items w.r.t. sizes  $e_1 \leq e_2 \leq \dots \leq e_m$  ( $a_i$  appears  $b_i$  times)
  - (2) Let  $G_1 = \{e_1, \dots, e_{\ell_1}\}$  be minimal set of items with  $\sum_{i \in G_1} e_i \geq 2$ , then continue with  $G_2, \dots$ . Let  $\ell_i := |G_i|$  be number of items in  $G_i$
  - (3) Remove first and last group  $\rightarrow$  waste
  - (4) From  $G_i$  throw away smallest  $\ell_i - \ell_{i+1}$  items  $\rightarrow$  waste
  - (5) Round up items in  $G_i$  to largest item  $\rightarrow I'$



## Geometric Grouping (2)

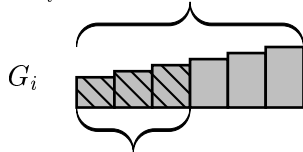
### Lemma

*Size of waste is  $O(\log \frac{1}{\delta})$ .*

- ▶ Size of 1st and last group is  $O(1)$
- ▶ Consider group  $G_i$ . Total size of items in  $G_i$  is  $\leq 3$ .
- ▶ Num of groups is  $\leq n/2$ . Clearly  $\frac{2}{\delta} \geq \ell_1 \geq \ell_2 \geq \dots$
- ▶ The  $n_i := \ell_i - \ell_{i+1}$  smallest items in  $G_i$  have size  $\leq 3 \frac{n_i}{\ell_i}$ .

$$\text{waste} \leq 3 \sum_i \frac{n_i}{\ell_i} \leq 3 \sum_{j=1}^{\ell_1} \frac{1}{j} \stackrel{\ell_1 \leq 2/\delta}{=} O(\log \frac{1}{\delta})$$

$\ell_i$  items of total size  $\leq 3$



$n_i$  items of total size  $\leq 3 \frac{n_i}{\ell_i}$

# The algorithm

## Algorithm:

- (1) Compute a basic solution  $x$  to  $P(\mathcal{P})$  with  $\mathbf{1}^T x \leq OPT_f + 1$
- (2) Buy  $\lfloor x_p \rfloor$  times pattern  $p$ , let  $I$  be remaining instance
- (3) Apply geometric grouping to  $I$  (with  $n$  different item sizes)  
 $\rightarrow I'$  (with  $n/2$  different item sizes)
- (4) Recurse

## Theorem

One has  $APX \leq OPT_f + O(\log^2 n)$ .

- ▶ Since  $x$  is basic solution,  $|\{p \mid x_p > 0\}| \leq n$ .
- ▶ After (2)  $size(I) \leq \sum_p (x_p - \lfloor x_p \rfloor) \leq n$ .
- ▶ Let  $x^t$  be solution  $x$  in iteration  $t$ . We buy  $\sum_p \lfloor x_p^t \rfloor$  bins, but  $OPT_f$  decreases by the same quantity.
- ▶ We pay in total  $OPT_f +$  total waste. We have  $O(\log n)$  recursions; in each recursion we have a waste of  $O(\log \frac{1}{\delta}) = O(\log n)$ .



## State of the art

- ▶ Computing  $OPT$  exactly is **NP**-hard even if the numbers  $a_i$  are unary encoded (i.e. BIN PACKING is **strongly NP**-hard).

### Open question

One can compute a BIN PACKING solution with  $\leq OPT + 1$  bins in poly-time?

### Mixed Integer Roundup Conjecture

One has  $OPT \leq \lceil OPT_f \rceil + 1$ .